

Common Fixed Point Theorem Sin $\mathfrak{R}$ -Partial B-Metricspaces

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Abstract: This paper deals with the mappings having the unique common fixed point theorem in $\mathfrak{R}$ -partial b-metricspaces with the property of $\mathfrak{R}$ -preserving and $\mathfrak{R}$ -property map.

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1 INTRODUCTION AND PRELIMINARIES

Due to the fact that Fixed Point theorem performs a vital role for dissimilar mathematical models to acquire its solutions. It has a broad range of applications in various mathematical fields.

In 1989, Bakhtin initiated the idea of b-metric space. The concept of "Common Fixed point theorems in b-metric space" was further extended by S. Czerwik [1] in the year 1993. Czerwik discovered to generalize the view of contraction mapping principle. In 1994, the idea of Partial metric space was discovered by Matthews [2]. In 2014, The concept of "Partial metric spaces" was further extended to "Partial b-metric spaces" by Shukla [3] and obtained some results in fixed point theorems. Newly, Gordji et al. [4] discovered the concept of orthogonal sets and some results in Fixed Point for contraction mappings. Presently, in 2020 Muhammad Usman Ali, Yajing Guo, Fahim Uddin, Hassen Aydi, Khalil Javed and Zhenhua Ma [8] stepped further in the field of common fixed point theorems for proposed contraction in $\mathfrak{R}$ -partial b-metric space.

A diverse number of researchers took intense attention in the generalized version of metric spaces as well as for common fixed point theorems.

Definition 1.1 [1]

Let S be a nonempty set and $g \geq 1$. Suppose a mapping $d : S \times S \rightarrow \mathbb{R}^+$

satisfies the following conditions for all $s, t, w \in S$:

$$(A1) \quad d(s, t) = 0 \text{ if and only if } s = t ; (A2)$$

$$d(s, t) = d(t, s);$$

$$(A3) \quad d(s, t) \leq g[d(s, w) + d(w, t)].$$

Then d is known as a b -metric on S , and (S, d) is called a b -metric space with coefficient g .

Definition 1.2 [2]

Let S be a nonempty set. Let $\delta: S \times S \rightarrow \mathbb{R}^+$ satisfy the following conditions for all $s, t, w \in S$:

$$(B1) \quad s = t \text{ if and only if } \delta(s, s) = \delta(s, t) = \delta(t, t);$$

$$(B2) \quad \delta(s, s) \leq \delta(s, t);$$

$$(B3) \quad \delta(s, t) = \delta(t, s);$$

$$(B4) \quad \delta(s, t) \leq \delta(s, w) + \delta(w, t) - \delta(w, w)$$

Then (S, δ) is called a partial metric space.

Definition 1.3 [3]

A partial b -metric on $S \neq \emptyset$ is a function $\sigma: S \times S \rightarrow \mathbb{R}^+$ such that for all $s, t, w \in S$, and for some $g \geq 1$, we have

$$(C1) \quad s = t \text{ if and only if } \sigma(s, s) = \sigma(s, t) = \sigma(t, t) ;$$

$$(C2) \quad \sigma(s, s) \leq \sigma(s, t)$$

$$(C3) \quad \sigma(s, t) = \sigma(t, s);$$

$$(C4) \quad \sigma(s, t) \leq g[\sigma(s, w) + \sigma(w, t)] - \sigma(w, w).$$

A partial metric space is denoted with (S, σ, g) . The number g is called the coefficient of (S, σ, g) .

Remark 1.4 [3]

It is clear that each and every partial metric space is a partial b -metric space having coefficient $g = 1$ and each b -metric space is a partial b -metric space with the identical constant and also having zero self-distance. However, the converse of this notion no longer holds.

Definition 1.5 [5]

Let S be a nonempty set. A subset $\mathcal{R}$ of S^2 is called a binary relation on S . Then, for any $s, t \in S$, we say that “ s is $\mathcal{R}$ -related to t ”, that is, $s \mathcal{R} t$, or “ s relates to t under $\mathcal{R}$ ” if and only if $(s, t) \in \mathcal{R}$. $(s, t) \notin \mathcal{R}$ means that “ s is not $\mathcal{R}$ -related to t ” or “ s is not related to t under $\mathcal{R}$ ”.

Definition 1.6 [5]

A binary relation $\mathcal{R}$ defined on a nonempty set S is called

- (a) reflexive if $(s, s) \in \mathcal{R} \forall s \in S$;
- (b) irreflexive if $(s, s) \notin \mathcal{R} \forall s \in S$;
- (c) symmetric if $(s, t) \in \mathcal{R}$ implies $(t, s) \in \mathcal{R} \forall s, t \in S$;
- (d) antisymmetric if $(s, t) \in \mathcal{R}$ and $(t, s) \in \mathcal{R}$ implies $s = t \forall s, t \in S$;
- (e) transitive if $(s, t) \in \mathcal{R}$ and $(t, w) \in \mathcal{R}$ implies $(s, w) \in \mathcal{R} \forall s, t, w \in S$;
- (f) preorder if $\mathcal{R}$ is both reflexive and transitive;
- (g) partial order if $\mathcal{R}$ is reflexive, antisymmetric, and transitive.

Definition 1.7 [6]

Let S be a nonempty set and let $\mathcal{R}$ be a binary relation on S .

- (a) A sequence $\{s_m\}$ is $\mathcal{R}$ -sequence if $\forall m \in \mathbb{N}, s_m \mathcal{R} s_{m+1}$
- (b) A map $P: S \rightarrow S$ is called an $\mathcal{R}$ -preserving if $\forall s, t \in S, s \mathcal{R} t$ implies $P s \mathcal{R} P t$

Definition 1.8 [6]

Let (S, d) be a metric space and $\mathcal{R}$ be a binary relation on S .

Then $(S, d, \mathcal{R})$ is called an $\mathcal{R}$ -metric space.

Definition 1.9[7]

A mapping $P: S \rightarrow S$ is $\mathfrak{R}$ -continuous at $s_0 \in S$ if for every $\mathfrak{R}$ -sequence $\{s_m\}_m \in \mathbb{N}$ in S with $s_m \rightarrow s_0$, we get $P(s_m) \rightarrow P(s_0)$. Thus, P is $\mathfrak{R}$ -continuous on S if P is $\mathfrak{R}$ -continuous at every $s_0 \in S$.

Definition 1.10[8]

Let $S \neq \emptyset$ and be a reflexive binary relation on S , which is denoted as $(S, \mathfrak{R})$. A map $\sigma_{\mathfrak{R}}: S \times S \rightarrow \mathbb{R}^+$ is called an $\mathfrak{R}$ -partial b-metric on the set S , if the following conditions are satisfied for all $s, t, w \in S$ with either $(s \mathfrak{R} t$ or $t \mathfrak{R} s)$, either $(s \mathfrak{R} w$ or $w \mathfrak{R} s)$ and either $(w \mathfrak{R} t$ or $t \mathfrak{R} w)$

$$(D1) \quad s = t \text{ if and only if } \sigma_{\mathfrak{R}}(s, s) = \sigma_{\mathfrak{R}}(s, t) = \sigma_{\mathfrak{R}}(t, t);$$

$$(D2) \quad \sigma_{\mathfrak{R}}(s, s) \leq \sigma_{\mathfrak{R}}(s, t);$$

$$(D3) \quad \sigma_{\mathfrak{R}}(s, t) = \sigma_{\mathfrak{R}}(t, s);$$

$$(D4) \quad \sigma_{\mathfrak{R}}(s, t) \leq g[\sigma_{\mathfrak{R}}(s, w) + \sigma_{\mathfrak{R}}(w, t)] - \sigma_{\mathfrak{R}}(w, w), \text{ where } g \geq 1.$$

Then, $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ is called $\mathfrak{R}$ -partial b-metric space with the coefficient $g \geq 1$.

Definition 1.11[8]

Let $\{s_m\}$ be a $\mathfrak{R}$ -sequence in $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ that is, $s_m \mathfrak{R} s_{m+1}$ or

$s_{m+1} \mathfrak{R} s_m$ for every $m \in \mathbb{N}$. Then,

- (a) $\{s_m\}$ is a convergent sequence to some $s \in S$ if $\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, s) = \sigma_{\mathfrak{R}}(s, s)$ and $s_m \mathfrak{R} s$ for each $m \geq k$.
- (b) $\{s_m\}$ is Cauchy if $\lim_{m, n \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, s_n)$ exists and is finite.

Definition 1.12 [8]

Let $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ is said to be $\mathfrak{R}$ -complete if for every Cauchy $\mathfrak{R}$ -sequence in S , there is $s \in S$ with $\lim_{n \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, s_n) = \lim_{n \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, s) = \sigma_{\mathfrak{R}}(s, s)$ and $s_n \mathfrak{R} s$ for each $m \geq k$.

Definition 1.13 [8]

We say that $P: S \rightarrow S$ is an $\mathfrak{R}$ -property map, if for any iterative $\mathfrak{R}$ -sequence $\{s_m : s_m = P^m s, s \in S\}$ in $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ with $\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, s) = \sigma_{\mathfrak{R}}(s, s)$, $s_m \mathfrak{R} s$ for some $m \geq k$ and $\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(s_m, Ps) \leq \sigma_{\mathfrak{R}}(s, s)$, we have that $s \mathfrak{R} P s$.

2 MAIN RESULT

Theorem 2.1:

Let $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ be an $\mathfrak{R}$ -complete $\mathfrak{R}$ -partial b-metric space with the coefficient $g \geq 1$ and permit $s_0 \in S$ such that $s_0 \mathfrak{R} t$ for every $t \in S$. Let $P: S \rightarrow S$ be an $\mathfrak{R}$ -preserving and $\mathfrak{R}$ -property map satisfying the following:

$$\sigma_{\mathfrak{R}}(Ps, Pt) \leq k[\sigma_{\mathfrak{R}}(s, Pt) + \sigma_{\mathfrak{R}}(t, Ps)] \text{ for all } s, t \in S \text{ with } s \mathfrak{R} t, \quad (1)$$

where $k \in (0, 1/g)$. Then, S has a fixed point $s^* \in S$ and $\sigma_{\mathfrak{R}}(s^*, s^*) = 0$.

Proof:

As $s_0 \in S$ such that $s_0 \mathfrak{R} t$ for every $t \in S$, then by using the $\mathfrak{R}$ -preserving nature of P , we construct an $\mathfrak{R}$ -sequence $\{s_m\}$ such that $s_m = P^{m-1}s_0$ and $s_{m-1} \mathfrak{R} s_m$ for every $m \in \mathbb{N}$.

We consider $s_m \neq s_{m+1}$ for every $m \in \mathbb{N} \cup \{0\}$.

Then, by (1), we obtain

$$\sigma_{\mathfrak{R}}(S_m, S_{m+1}) = \sigma_{\mathfrak{R}}(PS_{m-1}, S_m) \leq k[\sigma_{\mathfrak{R}}(S_{m-1}, PS_m) + \sigma_{\mathfrak{R}}(S_m, PS_{m-1})] \text{ for all } m \in \mathbb{N} \quad (2)$$

This inequality gives,

$$\sigma_{\mathfrak{R}}(S_m, S_{m+1}) \leq k^m [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] \text{ for all } m \in \mathbb{N} \quad (3)$$

We will consider an random integer $m \geq 1, n \geq 1$ with $n > m$ and also using (D4) on (3), we get

$$\begin{aligned} \sigma_{\mathfrak{R}}(S_m, S_n) &\leq g[\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + \sigma_{\mathfrak{R}}(S_{m+1}, S_n)] - \sigma_{\mathfrak{R}}(S_{m+1}, S_{m+1}) \\ &\leq g\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + g^2[\sigma_{\mathfrak{R}}(S_{m+1}, S_{m+2}) + \sigma_{\mathfrak{R}}(S_{m+2}, S_n)] - \sigma_{\mathfrak{R}}(S_{m+2}, S_{m+2}) \\ &\leq g\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + g^2\sigma_{\mathfrak{R}}(S_{m+1}, S_{m+2}) + g^3[\sigma_{\mathfrak{R}}(S_{m+2}, S_{m+2}) + \dots + g^{n-m}\sigma_{\mathfrak{R}}(S_{n-1}, S_n)] \\ &\leq g k^m [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] + g^2 k^{m+1} [\sigma_{\mathfrak{R}}(S_0, S_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] + g^3 k^{m+2} \\ &\quad [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] + \dots + g^{n-m} k^{n-1} [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] \\ &\leq g k^m [1 + gk + (gk)^2 + \dots] [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] \\ &= \frac{gk}{1-gk} [\sigma_{\mathfrak{R}}(S_0, PS_1) + \sigma_{\mathfrak{R}}(S_1, PS_0)] \end{aligned}$$

While $k \in [0, 1/g]$ and $g \geq 1$, it comes from the above inequality that

$$\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, S_n) = 0$$

Hence, $\{S_m\}$ is a Cauchy $\mathfrak{R}$ -sequence. Since S is $\mathfrak{R}$ -complete, there exists

$s^* \in S$ such that, $\lim_{m, n \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, S_n) = \lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, s^*) = \sigma_{\mathfrak{R}}(s^*, s^*)$ and $S_m \mathfrak{R} s^*$ for every

$m \geq k$ (for some value of k). Thus from the above, we get

$$0 = \lim_{m, n \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, S_n) = \lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, s^*) = \sigma_{\mathfrak{R}}(s^*, s^*) \text{ and } S_m \mathfrak{R} s^* \text{ for every}$$

$m \geq k$. While $S_m \mathfrak{R} s^*$ for every $m \geq k$, from (1), we obtain

$$\sigma_{\mathfrak{R}}(PS_m, PS^*) \leq k[\sigma_{\mathfrak{R}}(S_m, PS^*) + \sigma_{\mathfrak{R}}(s^*, PS_m)] \quad (5)$$

This inequality and therefore above findings imply

$$\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_{m+1}, PS^*) \leq k[\sigma_{\mathfrak{R}}(s^*, s^*) + \sigma_{\mathfrak{R}}(s^*, S_{m+1})]$$

$$\leq k[\sigma_{\mathfrak{R}}(s^*, s^*) + \sigma_{\mathfrak{R}}(s^*, s^*)]$$

$$=0$$

While $\mathfrak{S}$ is a $\mathfrak{R}$ -property map, hence we obtain $s^* \mathfrak{R} P s^*$ or $P s^* \mathfrak{R} s^*$. Without loss of generality, we are going to take $s^* \mathfrak{R} P s^*$. Then, by using (D4) with (1), we obtain the subsequent for every $m \geq k$.

$$\begin{aligned} \sigma_{\mathfrak{R}}(s^*, P s^*) &\leq g \sigma_{\mathfrak{R}}(s^*, s_{m+1}) + g \sigma_{\mathfrak{R}}(s_{m+1}, P s^*) - \sigma_{\mathfrak{R}}(s_{m+1}, s_{m+1}) \\ &\leq g \sigma_{\mathfrak{R}}(s^*, s_{m+1}) + g \sigma_{\mathfrak{R}}(P s_m, P s^*) \\ &\leq g \sigma_{\mathfrak{R}}(s^*, s_{m+1}) + g k [\sigma_{\mathfrak{R}}(s_m, P s^*) + \sigma_{\mathfrak{R}}(s^*, P s_m)] \end{aligned}$$

When m tends to infinity, the above inequality gives $\sigma_{\mathfrak{R}}(s^*, P s^*) = 0$.

Therefore we obtain $\sigma_{\mathfrak{R}}(s^*, P s^*) = 0$, $\sigma_{\mathfrak{R}}(s^*, s^*) = 0$ and $\sigma_{\mathfrak{R}}(P s^*, P s^*) = 0$.

Hence, $s^* = P s^*$, that is, s^* is a fixed point

Theorem 2:

Let $(S, \mathfrak{R}, \sigma_{\mathfrak{R}}, g)$ be a $\mathfrak{R}$ -complete $\mathfrak{R}$ -partial b-metric space having constant

$g \geq 1$ and permit $s_0 \in S$ such that $s_0 \mathfrak{R} t$ for every $t \in S$. Permit $P: S \rightarrow S$ be $\mathfrak{R}$ -preserving and an $\mathfrak{R}$ -property map satisfying the subsequent

$$\sigma_{\mathfrak{R}}(P s, P t) \leq a \sigma_{\mathfrak{R}}(s, P s) + b \sigma_{\mathfrak{R}}(s, P t) + c \sigma_{\mathfrak{R}}(s, t) \text{ for all } s, t \in S \text{ with } i \mathfrak{R} j, \quad (1)$$

where $a, b, c \in [0, 1/g]$. Then, S have a fixed point $s^* \in S$ and $\sigma_{\mathfrak{R}}(s^*, s^*) = 0$.

Proof:

As $s_0 \in S$ is such that $s_0 \mathfrak{R} t$ for every $t \in S$, then by using the $\mathfrak{R}$ -preserving

nature of P , we construct an $\mathfrak{R}$ -sequence $\{s_m\}$ such that $s_m = P s_{m-1} = P^m s_0$

and $s_{m-1} \mathfrak{R} s_m$ for every $m \in \mathbb{N}$. We inspect $s_m \neq s_{m+1}$ for every $m \in \mathbb{N} \cup \{0\}$.

Then, by (1), we obtain

$$\sigma_{\mathfrak{R}}(S_m, S_{m+1}) = \sigma_{\mathfrak{R}}(S_{m+1}, PS_m) \leq a\sigma_{\mathfrak{R}}(S_{m+1}, PS_{m-1}) + b\sigma_{\mathfrak{R}}(S_{m-1}, PS_m) + c\sigma_{\mathfrak{R}}(S_{m-1}, S_m) \quad (2)$$

for all $m \in \mathbb{N}$. This inequality gives,

$$\sigma_{\mathfrak{R}}(S_m, S_{m+1}) \leq a^m \sigma_{\mathfrak{R}}(S_0, PS_0) + b^m \sigma_{\mathfrak{R}}(S_0, PS_1) + c^m \sigma_{\mathfrak{R}}(S_0, S_1) \quad (3)$$

for all $m \in \mathbb{N}$. We will inspect a random integer $m \geq 1, n \geq 1$ with $n > m$ and use (3), we get

$$\begin{aligned} \sigma_{\mathfrak{R}}(S_m, S_n) &\leq g[\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + \sigma_{\mathfrak{R}}(S_{m+1}, S_m)] - \sigma_{\mathfrak{R}}(S_{m+1}, S_{m+1}) \\ &\leq g\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + g^2[\sigma_{\mathfrak{R}}(S_{m+1}, S_{m+2}) + \sigma_{\mathfrak{R}}(S_{m+2}, S_n)] - \sigma_{\mathfrak{R}}(S_{m+1}, S_{m+1}) \\ &\leq g\sigma_{\mathfrak{R}}(S_m, S_{m+1}) + g^2\sigma_{\mathfrak{R}}(S_{m+1}, S_{m+2}) + g^3[\sigma_{\mathfrak{R}}(S_{m+2}, S_{m+3})] + \dots + \\ &\quad g^{n-m}\sigma_{\mathfrak{R}}(S_{n-1}, S_n) \\ &\leq g[a^m\sigma_{\mathfrak{R}}(S_0, PS_0) + b^m\sigma_{\mathfrak{R}}(S_0, PS_0) + c^m\sigma_{\mathfrak{R}}(S_0, PS_0)] + \\ &\quad g^2[a^{m+1}\sigma_{\mathfrak{R}}(S_0, PS_0) + b^{m+1}\sigma_{\mathfrak{R}}(S_0, PS_0) + c^{m+1}\sigma_{\mathfrak{R}}(S_0, PS_0)] + \\ &\quad g^3[a^{m+2}\sigma_{\mathfrak{R}}(S_0, PS_0) + b^{m+2}\sigma_{\mathfrak{R}}(S_0, PS_1) + c^{m+2}\sigma_{\mathfrak{R}}(S_0, PS_0)] + \dots + \\ &\quad g^{n-m}[a^{n-1}\sigma_{\mathfrak{R}}(S_0, PS_0) + b^{n-1}\sigma_{\mathfrak{R}}(S_0, PS_0) + c^{n-1}\sigma_{\mathfrak{R}}(S_0, PS_0)] \\ &\leq \frac{g}{1-g} a^m \sigma_{\mathfrak{R}}(S_0, S_1) + \frac{gb^m}{1-gb} \sigma_{\mathfrak{R}}(S_0, S_1) + \frac{gc^m}{1-gc} \sigma_{\mathfrak{R}}(S_0, S_1) \end{aligned}$$

While $a, b, c \in [0, 1/g]$ and $g \geq 1$, it comes from above inequality that,

$$\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, S_n) = 0$$

Hence, $\{S_m\}$ is a Cauchy $\mathfrak{R}$ -sequence. Hence S is $\mathfrak{R}$ -complete, there exists $s^* \in S$ such that, $\lim_{m, n \rightarrow \infty} \sigma_{\mathfrak{R}}$

$$(S_m, S_n) = \lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, s^*) = \sigma_{\mathfrak{R}}(s^*, s^*) \text{ and } S_m \mathfrak{R} s^* \text{ for each}$$

$m \geq a, b, c$ (for some value of a, b, c). Then, from above, we get

$$0 = \lim_{m, n \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, S_n) = \lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_m, s^*) = \sigma_{\mathfrak{R}}(s^*, s^*) \text{ and } S_m \mathfrak{R} s^* \text{ for every}$$

$m \geq a, b, c$. While $S_m \models \mathcal{R}^*$ for every $m \geq a, b, c$ from (1), we obtain

$$\sigma_{\mathfrak{R}}(P S_m, P S^*) \leq a \sigma_{\mathfrak{R}}(S_m, P S_m) + b \sigma_{\mathfrak{R}}(S_m, P S^*) + c \sigma_{\mathfrak{R}}(S_m, S^*) \quad (5)$$

This inequality and the above findings simplify

$$\lim_{m \rightarrow \infty} \sigma_{\mathfrak{R}}(S_{m+1}, P S^*) \leq a \sigma_{\mathfrak{R}}(S^*, S_{m+1}) + b \sigma_{\mathfrak{R}}(S^*, S_{m+1}) + c \sigma_{\mathfrak{R}}(S^*, S^*)$$

$$\leq a \sigma_{\mathfrak{R}}(S^*, S^*) + b \sigma_{\mathfrak{R}}(S^*, S^*) + c \sigma_{\mathfrak{R}}(S^*, S^*)$$

$$= 0$$

While S is an $\mathfrak{R}$ -

property map, so we obtain $S^* \mathfrak{R} P S^*$ (or) $P S^* \mathfrak{R} S^*$. Without loss of generality, we will take $S^* \mathfrak{R} P S^*$. Then, by utilizing (D4) with (1), we obtain the subsequent for every $m \geq a, b, c$

$$\sigma_{\mathfrak{R}}(S^*, P S^*) \leq g \sigma_{\mathfrak{R}}(S^*, S_{m+1}) + g \sigma_{\mathfrak{R}}(S_{m+1}, P S^*) - \sigma_{\mathfrak{R}}(S_{m+1}, S_{m+1})$$

$$\leq g \sigma_{\mathfrak{R}}(S^*, S_{m+1}) + g \sigma_{\mathfrak{R}}(P S_m, P S^*)$$

$$\leq g \sigma_{\mathfrak{R}}(S^*, S_{m+1}) + g [a \sigma_{\mathfrak{R}}(S_m, P S_m) + b \sigma_{\mathfrak{R}}(S_m, P S^*) + c \sigma_{\mathfrak{R}}(S_m, S^*)]$$

When m tends to infinity, the above inequality gives $\sigma_{\mathfrak{R}}(S^*, P S^*) = 0$. Hence we obtain

$$\sigma_{\mathfrak{R}}(S^*, P S^*) = 0, \sigma_{\mathfrak{R}}(S^*, S^*) = 0 \text{ and } \sigma_{\mathfrak{R}}(P S^*, P S^*) = 0. \text{ Hence, } S^* = P S^*, \text{ that is, } S^* \text{ is a fixed point of } P.$$

Corollary 3.1:

Admit $(S, \sigma_{\mathfrak{R}}, g)$ be a $\mathfrak{R}$ -complete $\mathfrak{R}$ -partial b -metric space having constant $g \geq 1$ and permits $s_0 \in S$ such that $s_0 \mathfrak{R} t$ for every $t \in S$. Permit $P: S \rightarrow S$ be $\mathfrak{R}$ -preserving and an $\mathfrak{R}$ -property map satisfying the subsequent

$$\sigma_{\mathfrak{R}}(P s, P t) \leq a \sigma_{\mathfrak{R}}(s, P s) + b [\sigma_{\mathfrak{R}}(s, P t) + \sigma_{\mathfrak{R}}(s, t)] + c [\sigma_{\mathfrak{R}}(t, P s) + \sigma_{\mathfrak{R}}(t, P t)]$$

for all $s, t \in S$ with $s \mathfrak{R} t$, where $a, b, c \in [0, 1/g)$.

Then, P has a fixed point $s^* \in S$ and $\sigma_{\mathfrak{R}}(s^*, s^*) = 0$.

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